

Data sheet

DF ibex



Technical data

Type	-	DF1 ibex
Accuracy class	%	≤±0.02
Rated torque (Md _n)	Nm	500
Torque measuring system		
Technology	-	Rotating
Rated torque (Md _n) #1	Nm	500
Rated torque short measurement range (optional, minimum) (Md _{ns}) #2	Nm	N/A
Accuracy class extended (for Md _n)	%	N/A
Outputs	-	Frequency (RS422), Voltage, CAN bus, Alert
Test signal	-	see test report
Mechanical dimensions #3		
Outer diameter of rotor #4	mm	107
Lengths (Rotor, without centering)	mm	45
Pitch circle diameter #5	mm	84.0
Speeds and speed measuring systems		
Speed detection (integrated)	-	without
Speed detection (optional)	-	magn.
Maximum Speed without speed detection system	rpm	21,000
Optional increased speed	rpm	25,000
Maximum speed with magnetic speed encoder	rpm	14,000
Maximum speed with optical speed encoder	rpm	N/A
Maximum speed with inductive speed encoder	rpm	N/A
Torque accuracy class per output type (related to Md _n)		
Frequency output	%	≤±0.02
CAN output	%	≤±0.02
Voltage output	%	≤±0.04
Current output	%	N/A
Frequency output (option higher accuracy)	%	N/A
CAN (option higher accuracy)	%	N/A

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Type	-	DF1 ibex
Accuracy class	%	≤±0.02
Rated torque (Md _n)	Nm	500
Linearity deviation including hysteresis related to Md _n #6		
Frequency, 0%...30%	%	≤±0.010
Frequency, 30%...60%	%	≤±0.015
Frequency, 60%...100%	%	≤±0.020
CAN, 0%...30%	%	≤±0.010
CAN, 30%...60%	%	≤±0.015
CAN, 60%...100%	%	≤±0.020
Voltage output	%	≤±0.03
Current output	%	N/A
Rel. standard deviation of the reproducibility according to DIN 1319, by reference to variation of the output signal (rel. to Md _n)		
Frequency output	%	≤±0.020
CAN output	%	≤±0.020
Voltage output	%	≤±0.03
Current output	%	N/A
Temperature influence per 10K in the nominal temperature range on the output signal related to the actual value of signal span (rel. to Md _n)		
Frequency output	%	≤±0.02
CAN output	%	≤±0.02
Voltage output	%	≤±0.04
Current output	%	N/A
Temperature influence per 10K in the nominal temperature range on the zero signal (rel. to Md _n)		
Frequency output	%	≤±0.02
CAN output	%	≤±0.02
Voltage output	%	≤±0.04
Current output	%	N/A
Long-term drift over 48h at reference temperature		
Voltage output	mV	<1.5 / <3.0 / <0.8 / <1.5
Current output	µA	N/A

Technical data

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Accuracy class	%	≤±0.02
Rated torque (M _{dN})	Nm	500

Nominal sensitivity (range between zero torque and rated torque)

Frequency output	kHz	5 / 20 / 30 / 120
Voltage output	V	5.0 / 10.0 / 2.5 / 5.0
Current output	mA	N/A

Output signal at zero torque

Frequency output	kHz	10 / 60 / 60 / 240
Voltage output	V	0.0 / 0.0 / 2.5 / 5.0
Current output	mA	N/A

Nominal output signal

Frequency output at positive nominal value	kHz	15 / 80 / 90 / 360
Frequency output at negative nominal value	kHz	5 / 40 / 30 / 120
Voltage output at positive nominal value	V	5 / 10 / 5 / 10
Voltage output at negative nominal value	V	-5 / -10 / 0 / 0
Current output at positive nominal value	mA	N/A
Current output at negative nominal value	mA	N/A

Max. modulation range

Frequency output	kHz	0...420
Voltage output	V	-12.0...12.0
Current output	mA	N/A

Group delay time (main TCU)

Frequency output	µs	300
Voltage output	µs	300
CAN bus	µs	800

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Rated torque (M _{dN})	Nm	500

Speed measuring system		Inductive (track at rotor)
Pulse per rev (PPR)	ppr.	N/A
Maximum speeds (related to PPR)	rpm	N/A
Max. output frequency (RS422)	kHz	N/A
Minimum speed for sufficient pulse stability	rpm	N/A
Speed measuring system		Magneto resistive (2 tracks approx. 90 degree phase shifted)
Pulses per rev (PPR)	ppr.	680
Maximum speeds (related to PPR)	rpm	14,000
Max. output frequency (RS422)	kHz	159
Minimum speed for sufficient pulse stability	rpm	>0.1
Nominal clearance (sensor - pole ring)	mm	0.7
Working airgap (sensor - pole ring)	mm	0.1...1.0
Nominal axial displacement (rotor - stator) #7	mm	7.0
Tolerance to nominal axial displacement (rotor - stator)	mm	±0.5
Speed measuring system		Optical
Pulses per rev (PPR)	ppr.	N/A
Maximum speeds (related to PPR)	rpm	N/A
Max. output frequency (RS422)	kHz	N/A
Minimum speed for sufficient pulse stability	rpm	N/A
Nominal radial displacement (rotor - stator)	mm	N/A
Tolerated radial displacement (rotor - stator) #7	mm	N/A
Nominal axial displacement (rotor - stator) #7	mm	N/A
Tolerance to nominal axial displacement (rotor - stator)	mm	N/A

Technical data

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Rated torque (M _{dN})	Nm	500

Angular measuring system

Requirement	-	Optional magnetic speed detection
Pulses per rev	ppr.	680
Resolution	°	0.132
Output signals	-	CAN bus, Voltage
Measurement ranges	°	0.00...360.00 / -180.00...180.00 / -360.00...360.00 / -720.00...720.00 / -1,080.00...1,080.00 / -1,440.00...1,440.00 / -1,800.00...1,800.00

Technical data

Type	-	DF1 ibex
Accuracy class	%	≤±0.02
Rated torque (Md _n)	Nm	500
Temperature ranges		
Nominal temperature range (Rotor)	°C	0...80
Operating temperature range (Rotor) #8	°C	-20...85
Storage temperature range (Rotor)	°C	-30...85
Nominal temperature range (Stator)	°C	0...80
Operating temperature range (Stator) #9	°C	-20...85
Storage temperature range (Stator)	°C	-30...85
Nominal temperature range (TCU)	°C	0...70
Operating temperature range (TCU)	°C	-20...70
Storage temperature range (TCU)	°C	-30...85
Mechanical shock (EN 60068-2-27)		
Quantity	-	1,000
Duration	ms	3
Acceleration	m/s²	650
Vibration load (EN 60068-2-6)		
Frequency	Hz	10...2,000
Duration	min.	150
Acceleration	m/s²	200
Load limits #10		
Limit torque, related to Md _n	%	350
Breaking torque approx., related to Md _n	%	625
Axial limit force	kN	8.10
Lateral limit force	N	2,620.00
Bending limit torque	Nm	63.00

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Rated torque (Md _n)	Nm	500

Mechanical values		
Torsional stiffness	kNm/rad	263
Angle of twist at Md _n	°	0.109
Axial stiffness	kN/mm	325
Radial stiffness	kN/mm	174
Bending stiffness	kNm/°	1.50
Deflection at axial limit force	mm	<0.03
Additional radial deviation at lateral limit force	mm	<0.02
Parallel deviation at bending limit torque	mm	<0.08
Inherent frequency	Hz	1,740
Balance quality-level (DIN ISO 1949)	-	G2.5
Inertia of rotor	kgm²	0.0017
Max. limits for relative shaft vibration (peak to peak) #11	µm	$S_{(p-p)} = \frac{9000}{\sqrt{n}}$

Technical data

Type	-	DF1 ibex
Accuracy class	%	≤±0.02
Rated torque (M _{dN})	Nm	500
Weight approx.		
Rotor #12	kg	1.2
Stator (without speed encoder) #12	kg	0.90
Mounting distances (without optional speed detection system)		
Nominal radial displacement (rotor - stator)	mm	139.0
Tolerance to nominal radial displacement (rotor - stator)	mm	+0.2/-0.2
Nominal axial displacement (rotor - stator) #7	mm	7.0
Tolerance to nominal axial displacement (rotor - stator)	mm	≤±0.5
Flatness and concentricity tolerances rotor		
Circular run-out-axial tolerance #13	mm	0.01
Circular run-out-radial tolerance #13	mm	0.01
Power supply		
Nominal supply	V	(DC) 24
Supply range #14	V	(DC) 23...25
Max. current consumption in measuring mode	A	<1
Max. current consumption in start-up mode	A	<2
Nominal power consumption	W	<24
Load resistance		
Frequency output	-	RS422
Voltage output	kOhm	≥50
Dynamic		
Frequency output	kHz	≤6
Voltage output	kHz	≤6
Current output	kHz	N/A
CAN output conversation rate	1/s	≤2,000

Technical data

Type	-	DF1 ibex
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Rated torque (Mdn)	Nm	500
Miscellaneous		
Protection class (Rotor)	-	IP54
Protection class (Stator)	-	IP54
Protection class (rotor, extended)	-	N/A
Protection class (stator, extended)	-	N/A
Pitch circle screw information	-	6 * M8 (12.9)
CAN bus type	-	2B
Configuration interface	-	Ethernet
Central hole	mm	N/A
Material	-	Steel
Measuring range (related to Mdn)	%	110
Compatible evaluation units (TCU)	-	TCU5
Stator type	-	DF1 ibex
Sales information		
Article number	-	10008268
U.S. FCC certificate	-	No

Remarks and information

Link no.	Topic	Remark
#1	Nominal torque	Based on customer requests, the measurement systems can optionally be optimized for not listed nominal torque values (intermediate ranges possible).
#2	Second torque range	<p>The written second nominal torque value ($M_{d_{ns}}$) is the smallest possible. Greater second torque ranges can be chosen on demand.</p> <p>Mechanical values and load limits vary between single and dual range torque meters. A data sheet for dual range torque meters with specific values can be requested.</p>
#3	Dimensions	Mechanical dimensions are without engagement. Use the drawings and step files as master for your constructions.
#4	Details in the drawings	Value can vary by optional components. Please find details to this attribute in the integrated drawings.
#5	Pitch circle diameter	The pitch circle diameter is identically at input and output side for most systems. More information is given in the drawings of a product.
#6	Linearity	Values of Linearity deviation incl. Hysteresis can only be reached if positive and negative sensitivity values are used.
#7	Reference planes	Please check the drawings for information about the reference planes of this attribute.
#8	Temperature range (rotor)	No condensation allowed.
#9	Temperature range (stator)	No condensation allowed. Temperature related to housing ground point.
#10	Load limits	<p>The given values are only valid if no other load occurs at the same time. If the loads in sum are 100%, the max. error will be 0.3% of the nominal torque.</p> <p>Limit and break torque are lower if other loads are applied (such as lateral forces).</p>

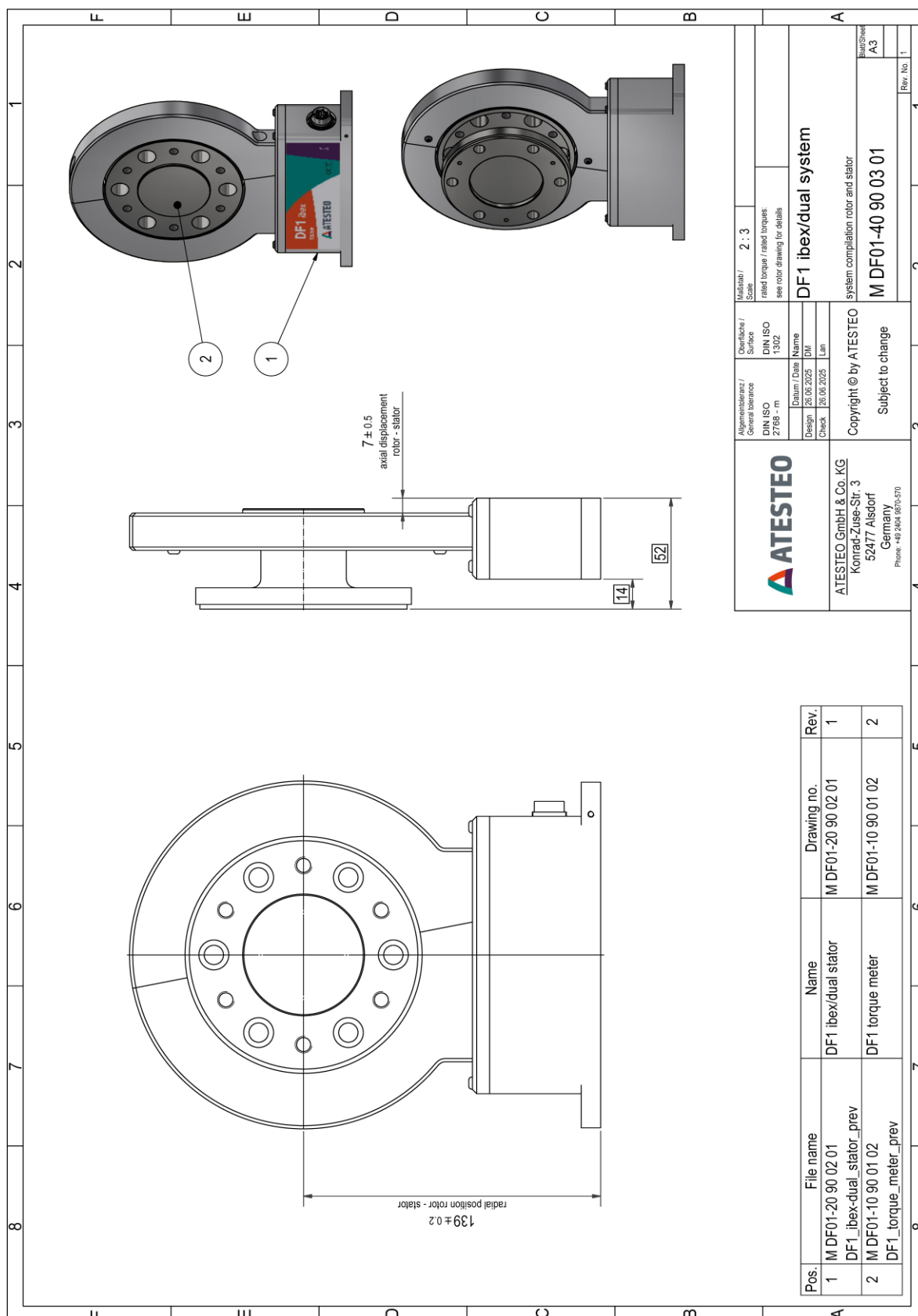
Remarks and information

Link no.	Topic	Remark
#11	Vibration limits	Vibration limits are not an influence to the machine. They reflect the allowed effect onto the rotor (ISO 7919-3). Parameter "n" is given in "r/min."
#12	Weights	Weights are related to components without options like speed detection system. Please contact us for exact weight information of options.
#13	Flatness and concentricity tolerances	The parameters of "Flatness and concentricity tolerances rotor" are manufacturing tolerances.
#14	Supply voltage	The supply voltage range must be given at measurement system side. Long wires can reduce the voltage level from power supply to measurement system.

Drawing



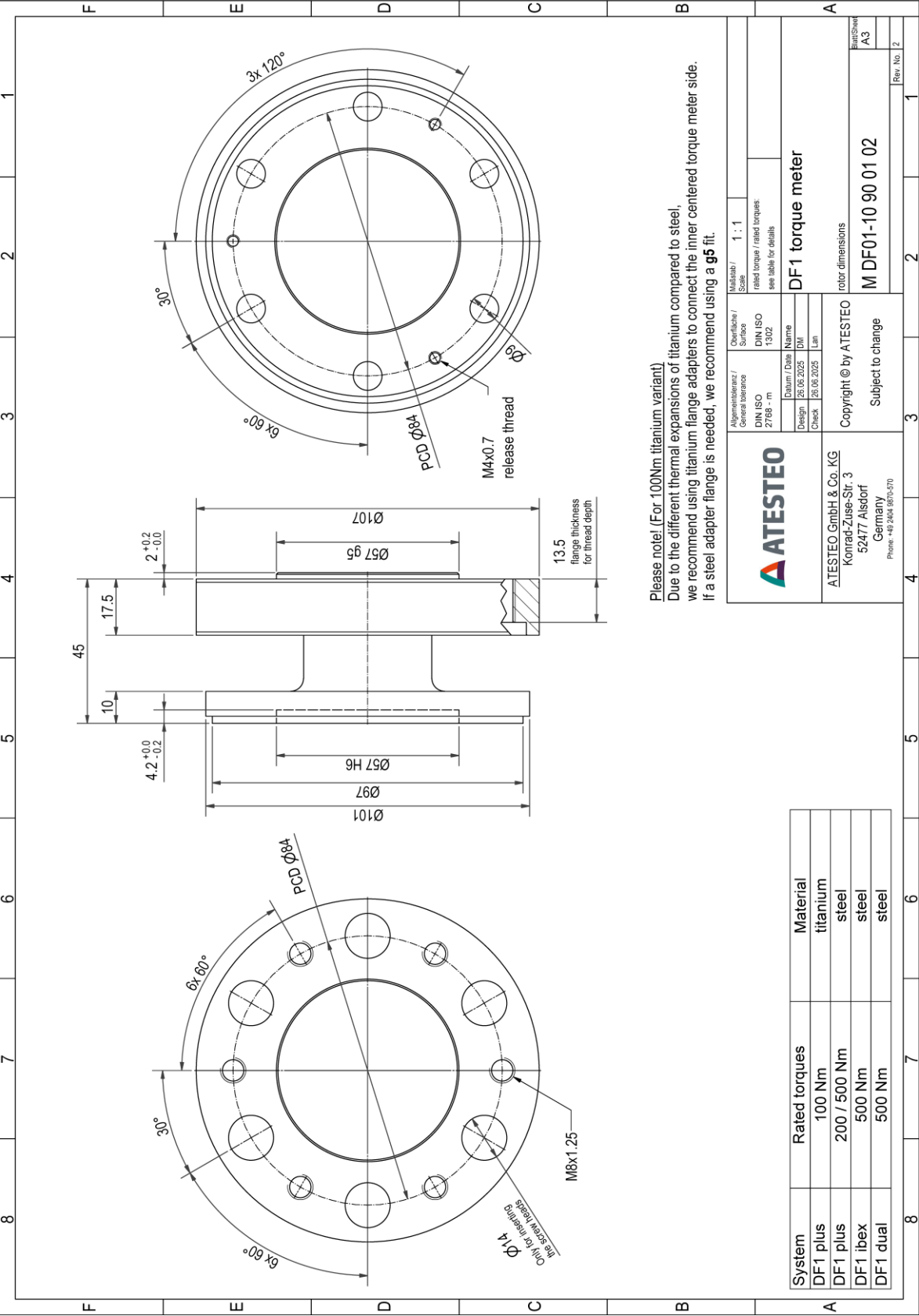
Drawing



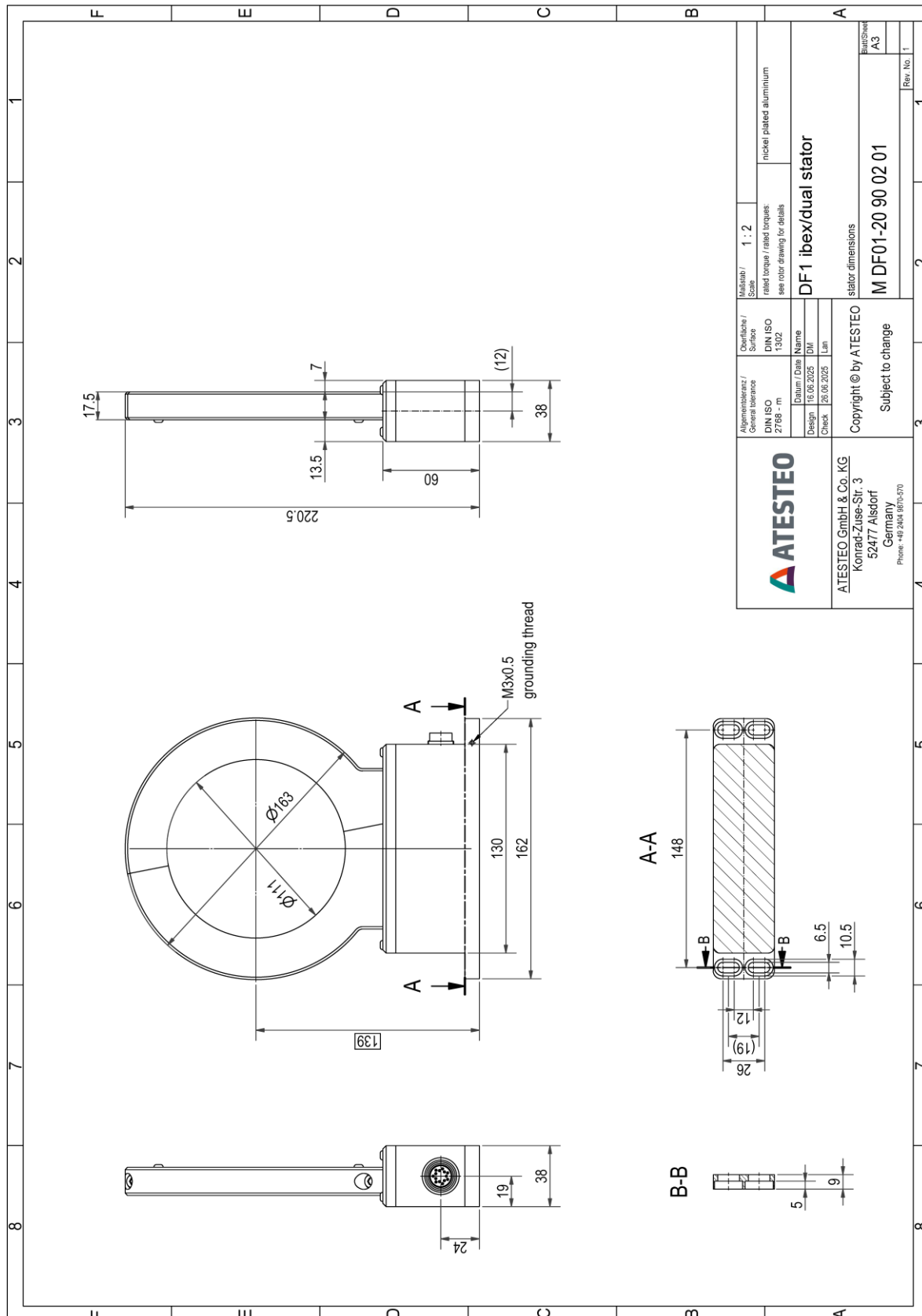
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Drawing



Drawing



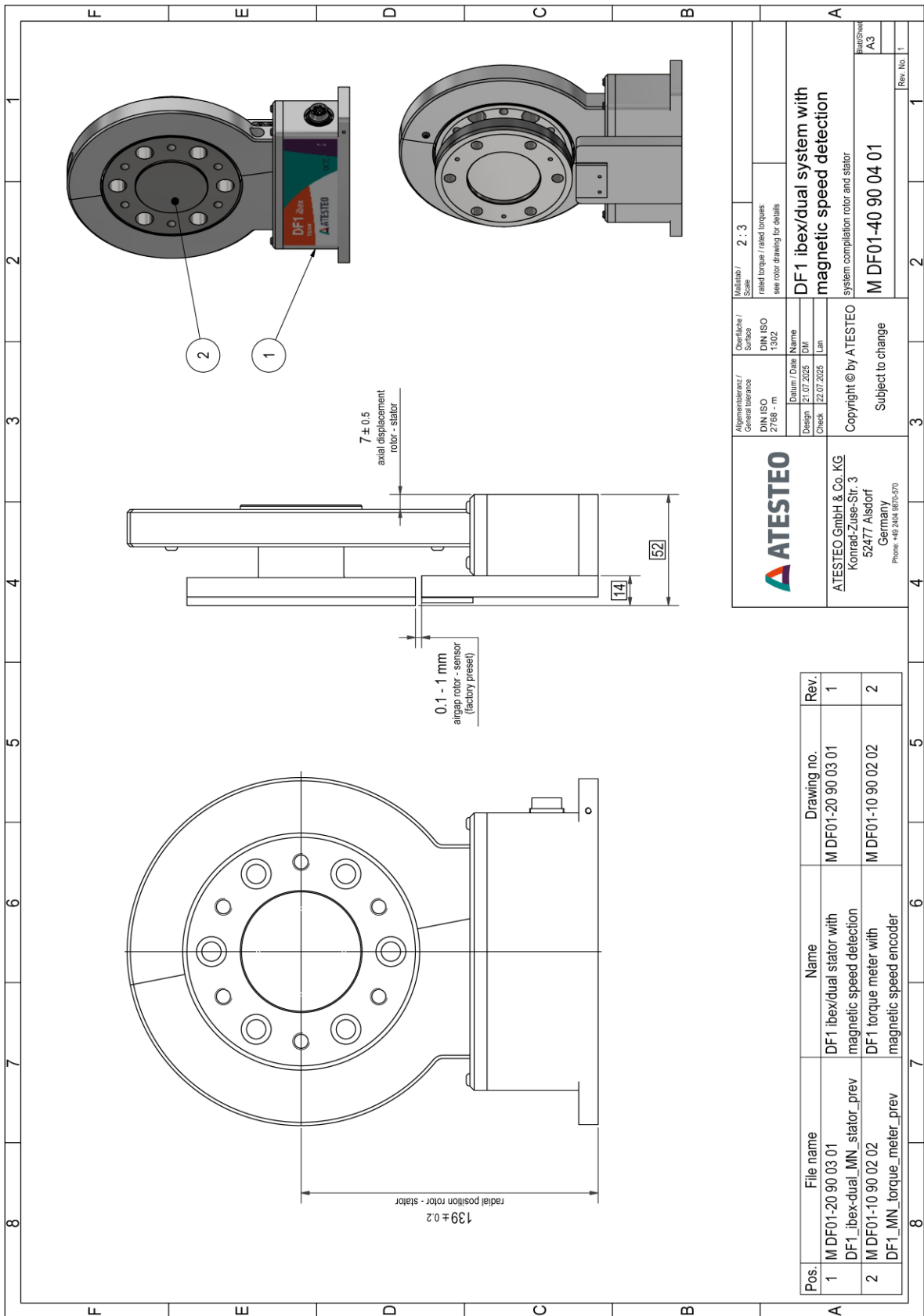
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DF1 ibex SPD_MGN System

DF1 ibex

Drawing



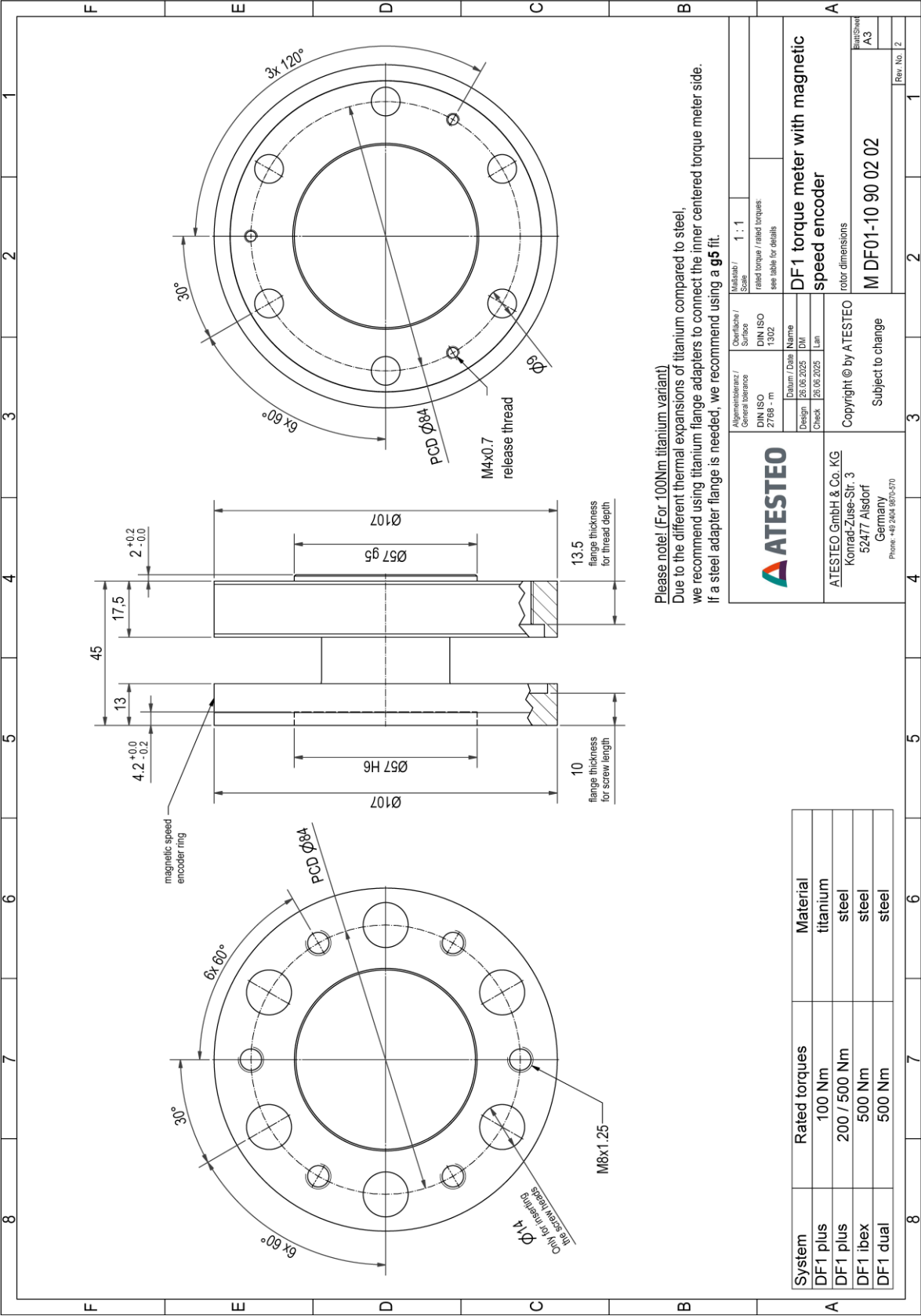
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DF1 ibex SPD_MGN
Rotor

DF1 ibex

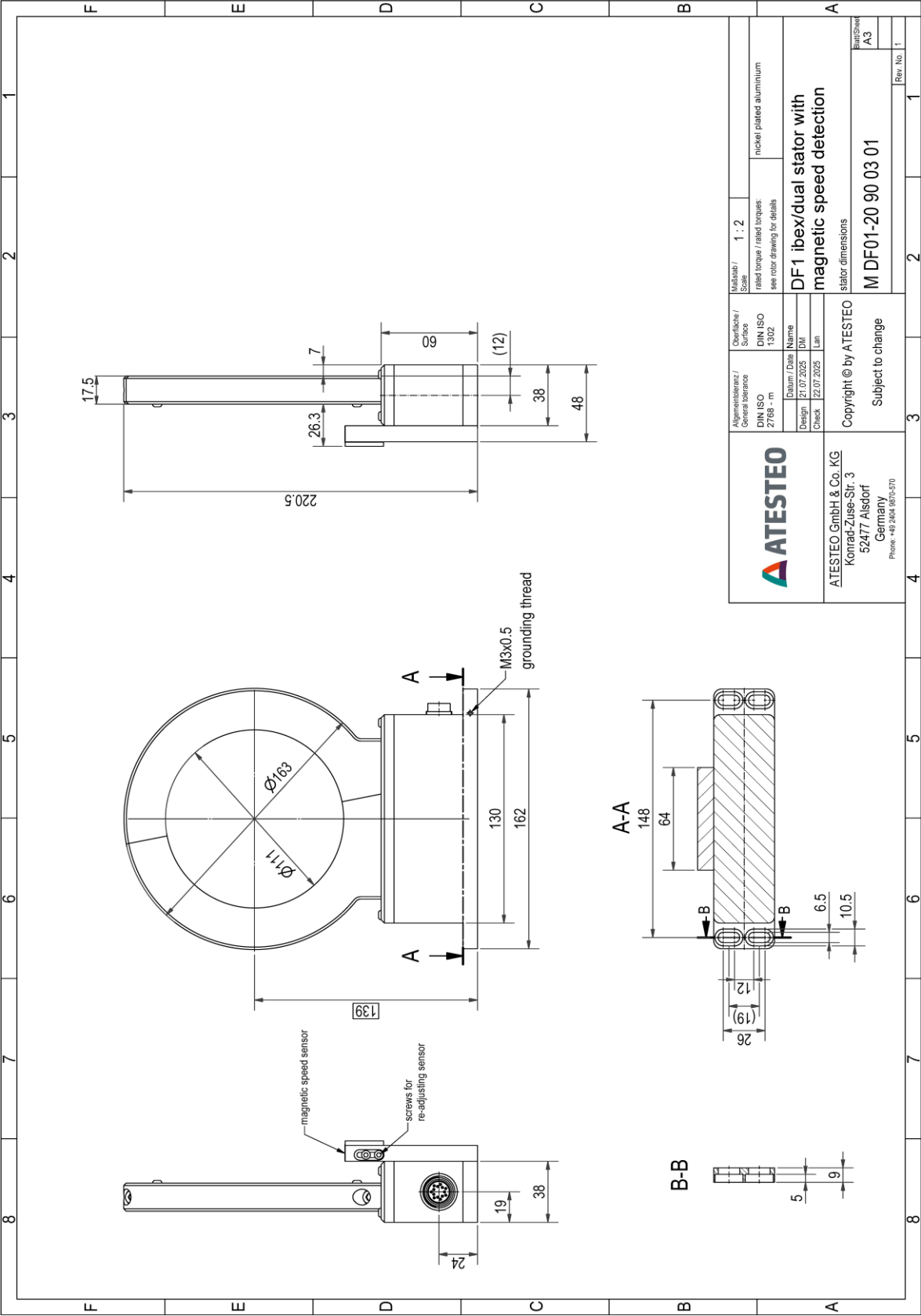
Drawing



DF1 ibex SPD_MGN
Stator

DF1 ibex

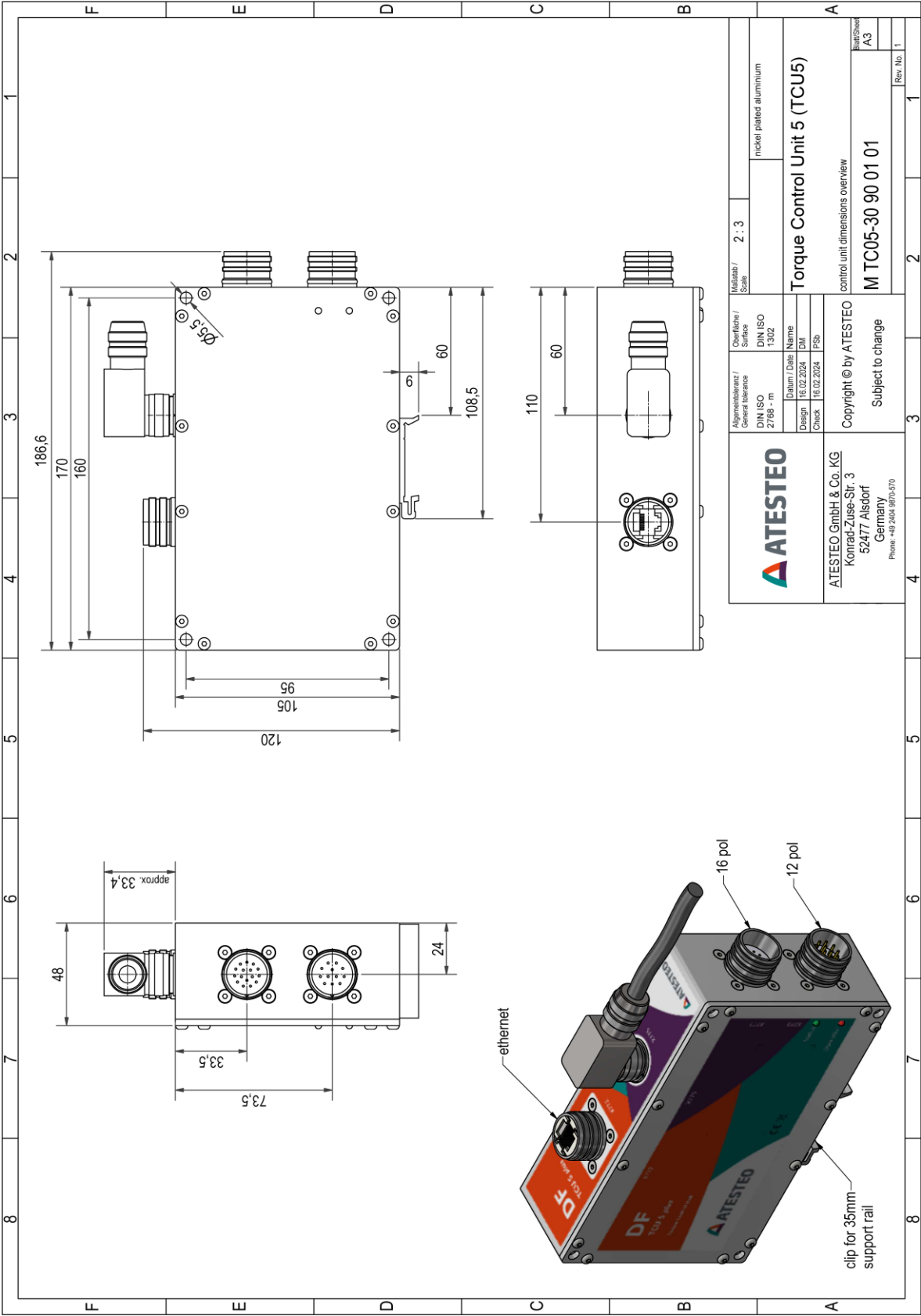
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Drawing



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